

Mathematical Models

In this chapter, we consider the problem of differential equation in coordinate geometry and in science and engineering. We formulate the problem mathematically thereby obtaining a differential equation, then we solve the equation.

1. Application in Coordinate Geometry :-

1.Q. In the following problems, a function $y=h(x)$ is described by some geometric property of its graph. Write a d. eqn of the form $\frac{dy}{dx} = f(x, y)$ having the function h as its solution.

(i) Every straight line normal to the graph of h passes through the point $(0, 1)$.

(ii) The line tangent to the graph of h at (x, y) passes through the point $(-y, x)$.

(iii) The graph of h is normal to every curve of the form $y = x^2 + k$, where k is a constant, where they meet.

Solⁿ :- (i) Slope of tangent at the point $(x, y) = \frac{dy}{dx}$ then the slope of the normal = $-\frac{1}{\frac{dy}{dx}}$.

The eqⁿ of straight line passing through the point $(0, 1)$ and slope $-\frac{1}{\frac{dy}{dx}}$ is

$$(y-1) = -\frac{1}{\frac{dy}{dx}} (x-0)$$

$$\Rightarrow \frac{dy}{dx} = \frac{-x}{y-1}$$

which is the reqd eqⁿ of the normal passes through (0,1).

(ii) \Rightarrow The eqⁿ of the tangent with slop $\frac{dy}{dx}$ and passing through the point $(-y, x)$ is,

$$y - x = \frac{dy}{dx} (x + y)$$

$$\Rightarrow \frac{dy}{dx} = \frac{y - x}{y + x}$$

(iii) \Rightarrow Slope of the tangent $= m = \frac{dy}{dx}$.

slope of the normal to the curve $y = x^2 + k$ is

$$m_1 = \frac{d(x^2 + k)}{dx} = 2x.$$

By condition of orthogonality, $m m_1 = -1$.

$$\Rightarrow \frac{dy}{dx} \cdot 2x = -1 \Rightarrow \frac{dy}{dx} = \frac{-1}{2x}.$$

Thus, the reqd d. eqⁿ is, $\frac{dy}{dx} = \frac{-1}{2x}$.

2. Applications of Differential Equation in Science and Engineering:-

Newton's Second Law :- The time rate change of momentum of a body is proportional to the resultant force acting on the body and is in the direction of this resultant force.

In mathematical form,

$\frac{d}{dt} (mv) = kF$, where m is the mass of body, v is velocity and F is resultant force acting upon it and k is constant of proportionality and m is constant, then-

$$m \frac{dv}{dt} = kF \Rightarrow ma = kF \Rightarrow F = \frac{1}{k} ma$$

$$\Rightarrow F = ma \text{ if } k=1.$$